



High-Fidelity Transmission Simulation for Vehicle Dynamics Simulations

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Topics

- Introduction – Model Based Development
- The MapleSim Solution
- The Driveline Component Library
- Advantage of the Symbolic Technology
- MapleSim and VI-CarRealTime
- Summary

Physical Model-Based Development

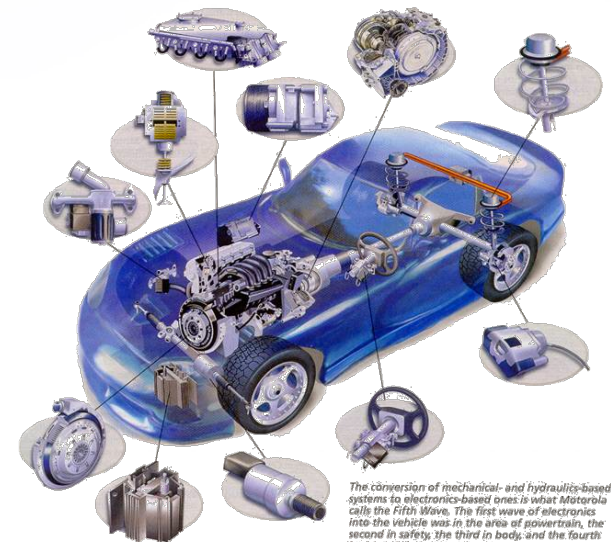
“Virtual” Prototyping through Model-based Design and Development plays an increasingly key role in powertrain design and development.

- Increasing adoption of MBD and simulation
 - Reduce prototyping cycles and costs
 - Increase end-user functionality, quality, safety and fuel-efficiency
 - Deterministic, repeatable testing platform

Modeling the whole vehicle provides greater insight into overall energy losses and how to reduce them

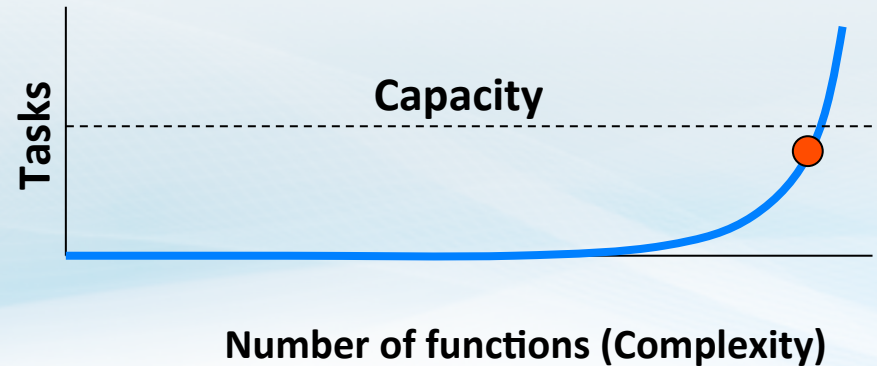
- Energy loss through individual subsystems
- Efficiency losses through interaction between subsystems

Greater demand for greater model fidelity...

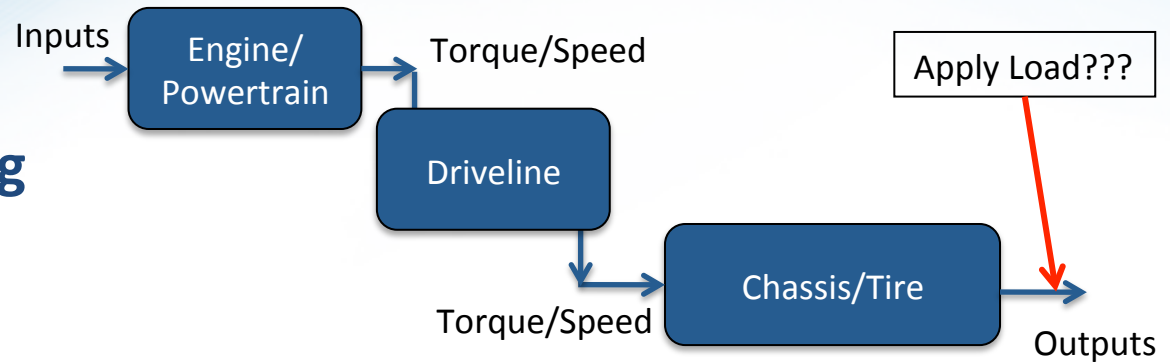


Emerging Challenges

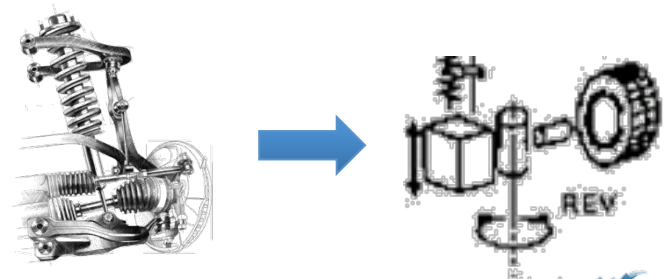
Scalability



Multi-domain Modeling

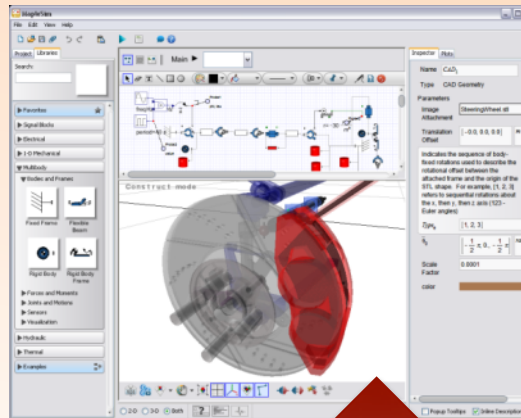


Real-time Performance



The MapleSim Solution

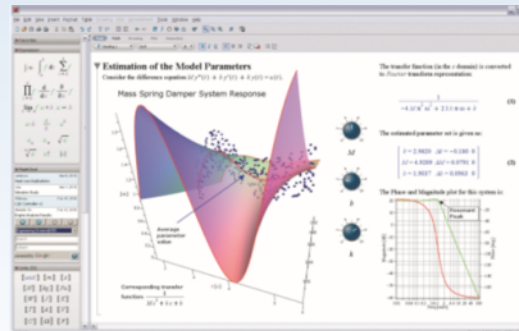
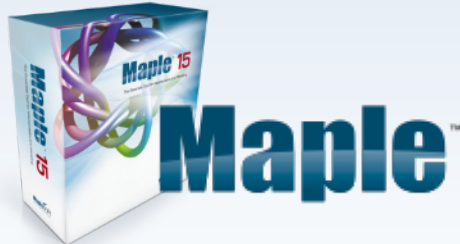
Multidomain physical modeling
and simulation



MapleSim Connector

Control Design Toolbox Tire Component Library Driveline Component Library More Libraries

Analysis environment



Global Optimization

MapleNet

GRID Computing

dSPACE

LabVIEW

NI VeriStand

MATLAB & SIMULINK

Automation Studio

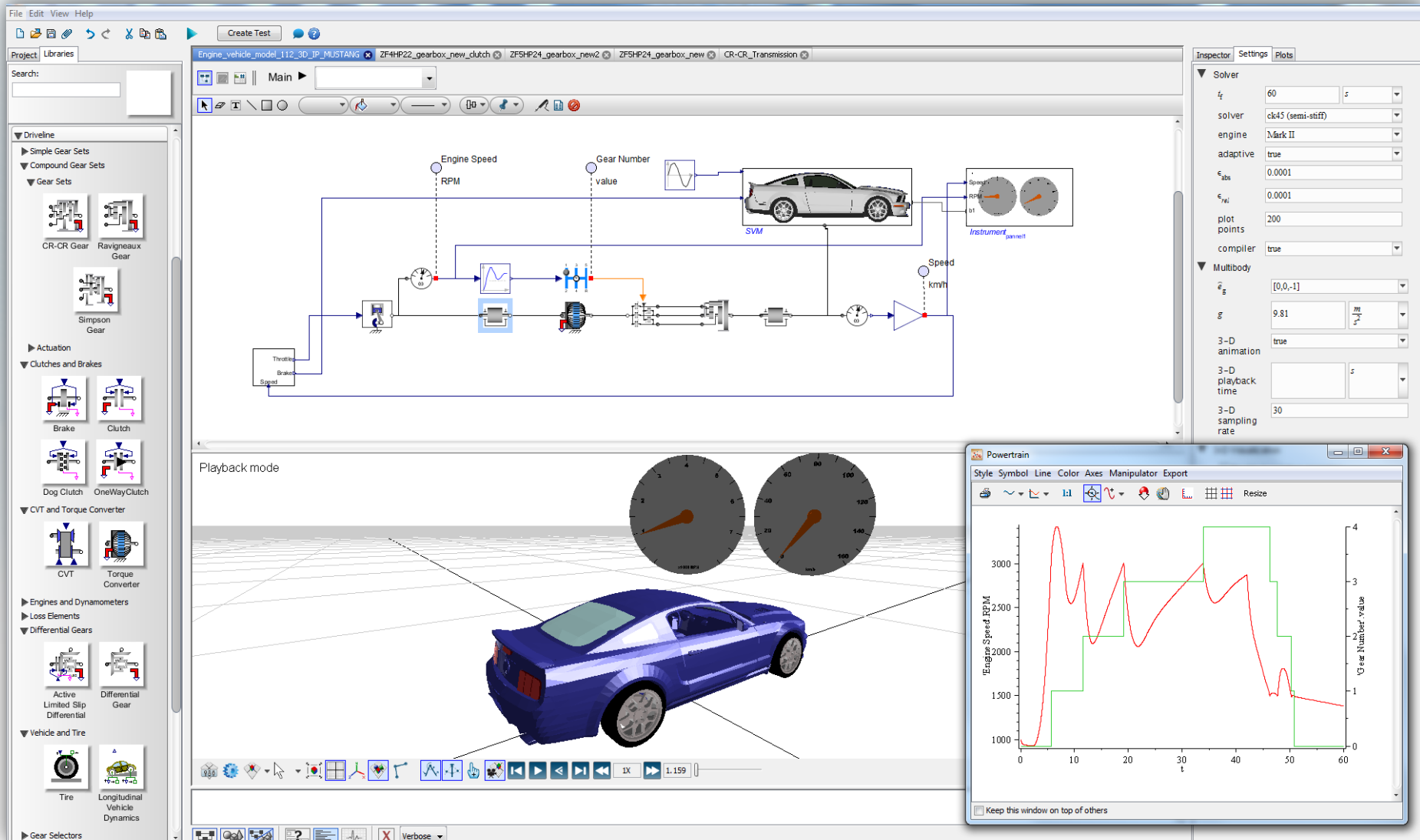
VI grade

engineering software & services

modelisar

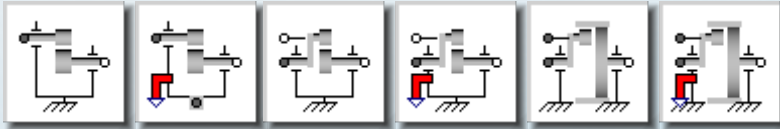
Functional Mock-up Interface

MapleSim Modeling Environment



Driveline Component Library

Simple Gear Sets



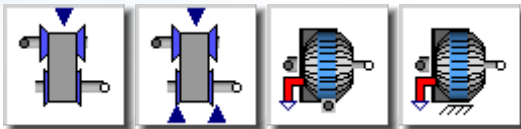
Compound Gear Sets



Differentials



CVT and Torque Converter



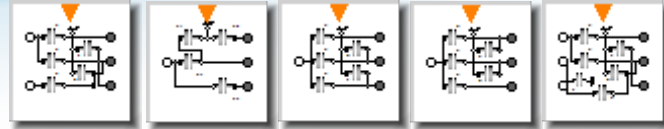
Vehicle Dynamics



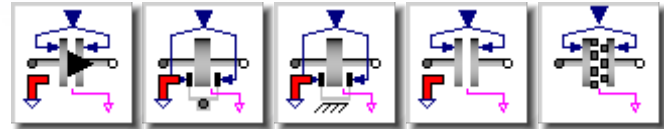
Planetary Gear Sets



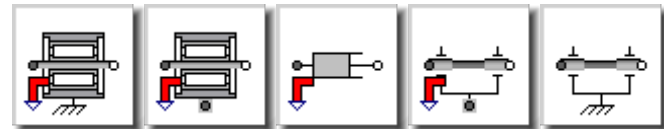
Actuation Components



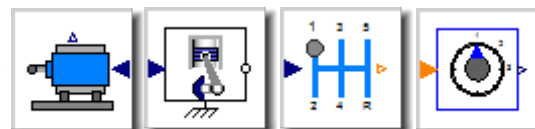
Brakes and Clutches



Loss Components



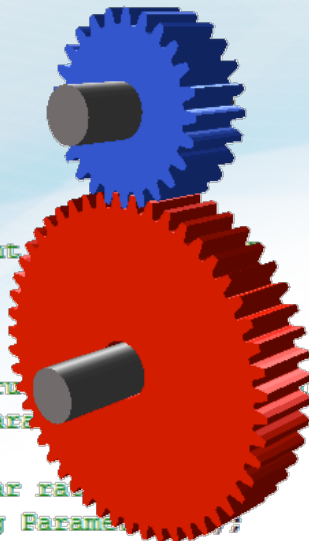
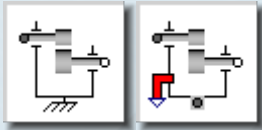
Dyno, Engine, Gear Shifter



Modeling Gear Sets

Simple Gear Sets

- Basic Gear



```

model BasicGear "Mass-less gear element"

import Modelica.Blocks.Types;

parameter Boolean ideal=true "= true: ideal, false: non-ideal"
annotation(Dialog(tab="Modeling Parameters",enable=not ideal));

parameter Real ratio(start=1) "Gear ratio"
annotation(Dialog(tab="Engineering Parameters",enable=not ideal));

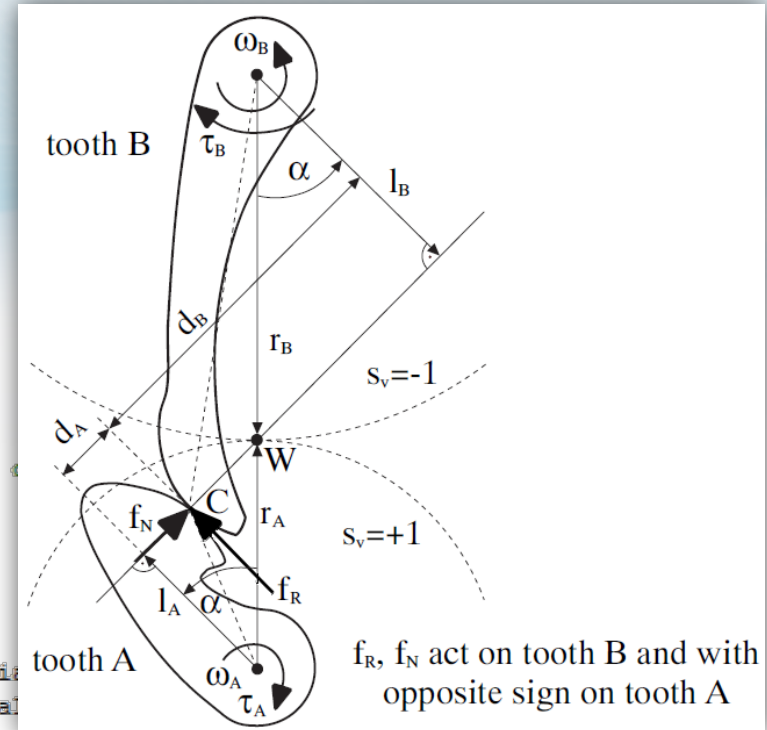
parameter DataSourceMode4 datasourcemode=DataSourceMode4.ViaFile
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parameter String fileName="DataFileName" "Enter the file (complete path) where matrix is stored"
annotation(Dialog(tab="Engineering Parameters",enable=not ideal and datasourcemode==DataSourceMode4.OnFile));

parameter String data(categories="datasets")="none selected" "Attached Data Set"
annotation(Dialog(tab="Engineering Parameters",enable=not ideal and datasourcemode==DataSourceMode4.Attachment));

parameter Real columns[1, :]=[2, 3] "Data columns used"
annotation(Dialog(tab="Engineering Parameters",enable=not ideal and (datasourcemode==DataSourceMode4.OnFile or datasourcemode==DataSourceMode4.Attachment)));

parameter Real inputNo=1 "Number of loss data inputs used"
annotation(Dialog(tab="Modeling Parameters",enable=not ideal and datasourcemode==DataSourceMode4.External));
    
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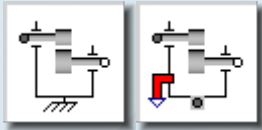


Pelchen C., Schweiger C., Otter M.
Modeling and Simulating the Efficiency of Gearboxes and of Planetary Gearboxes
 2nd International Modelica Conference, Proceedings, pp. 257-266

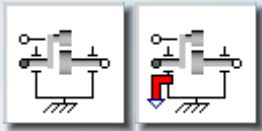
Modeling Gear Sets

Simple Gear Sets

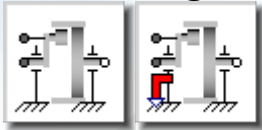
- Basic Gear



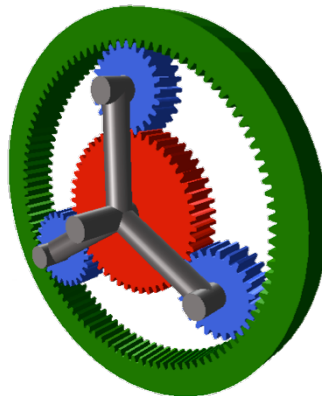
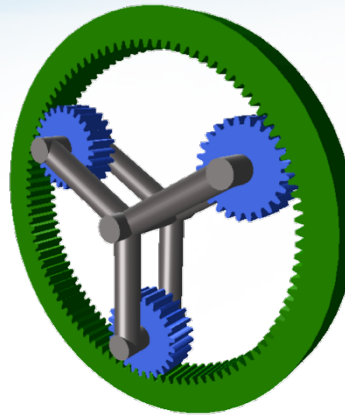
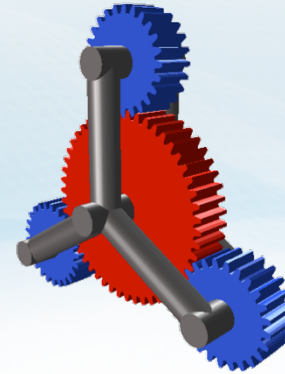
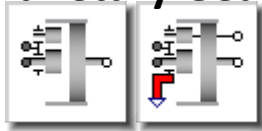
- Planet Planet Gear



- Planet Ring Gear



Planetary Gear

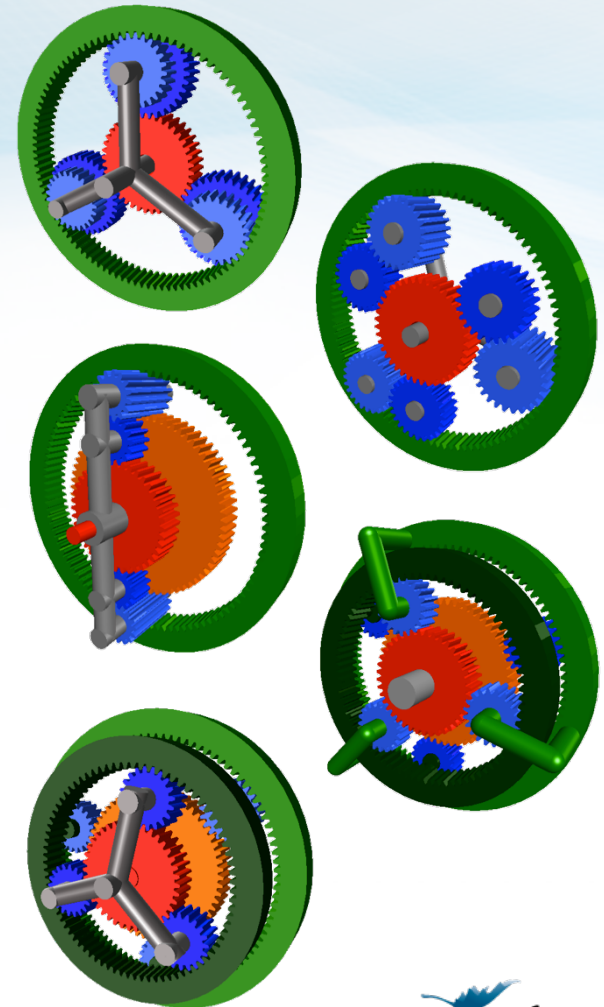
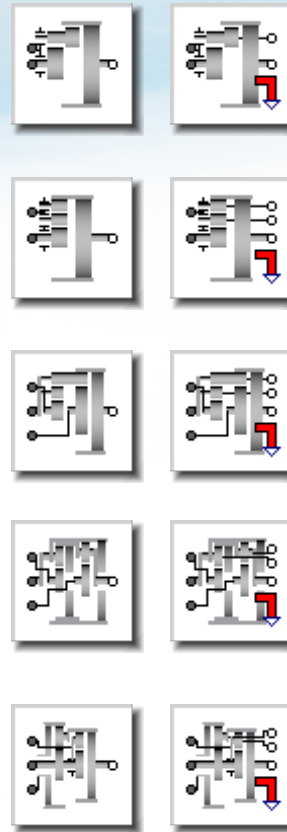


Driveline Component Library

Compound Gear Sets

Gear Sets:

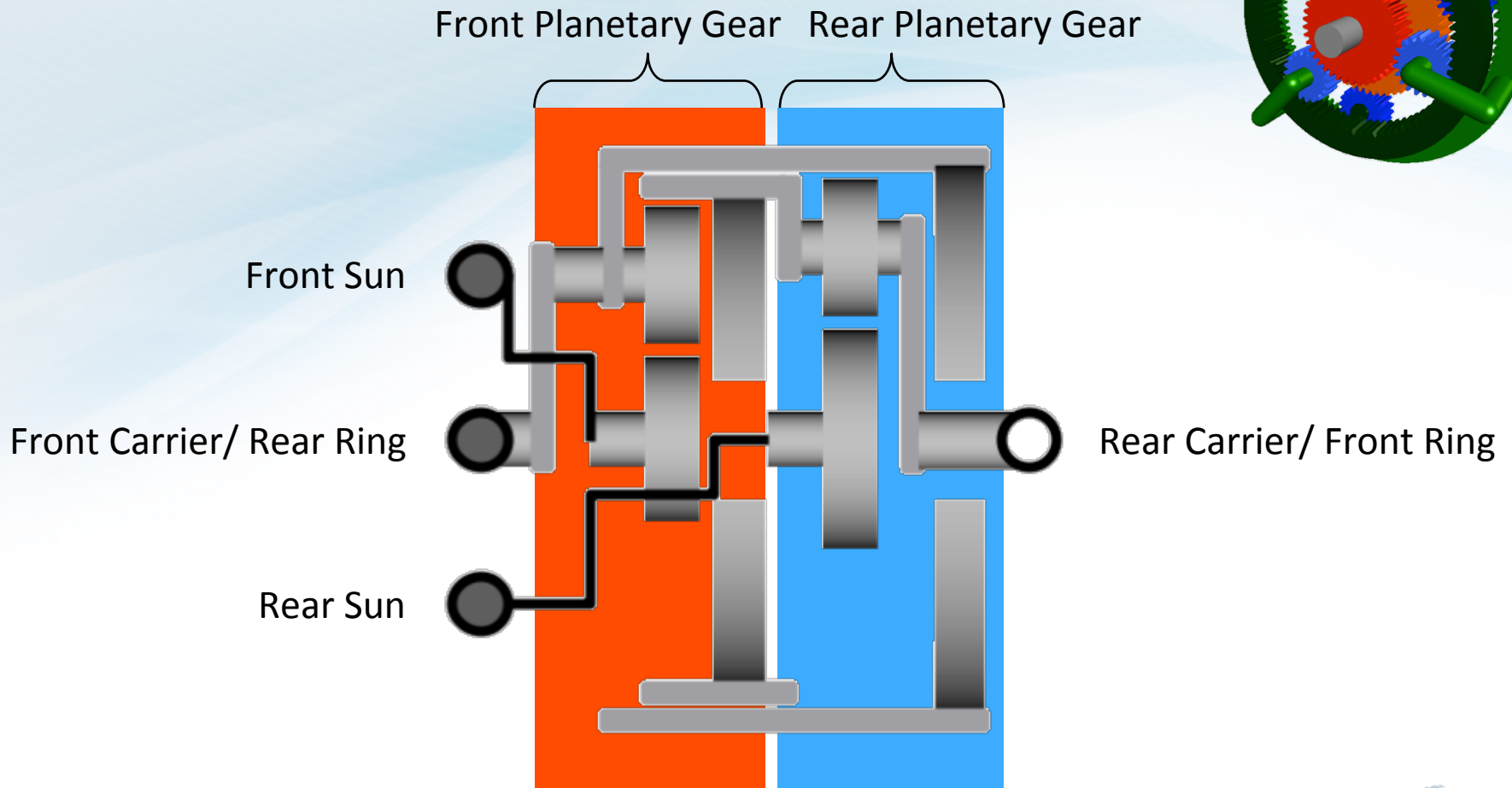
- Dual-Ratio Planetary Gear
- Counter-Rotating Planetary Gear
- Ravigneaux Gear Set
- CR-CR Gear Set
- Simpson Gear Set



Driveline Component Library

Compound Gear Sets

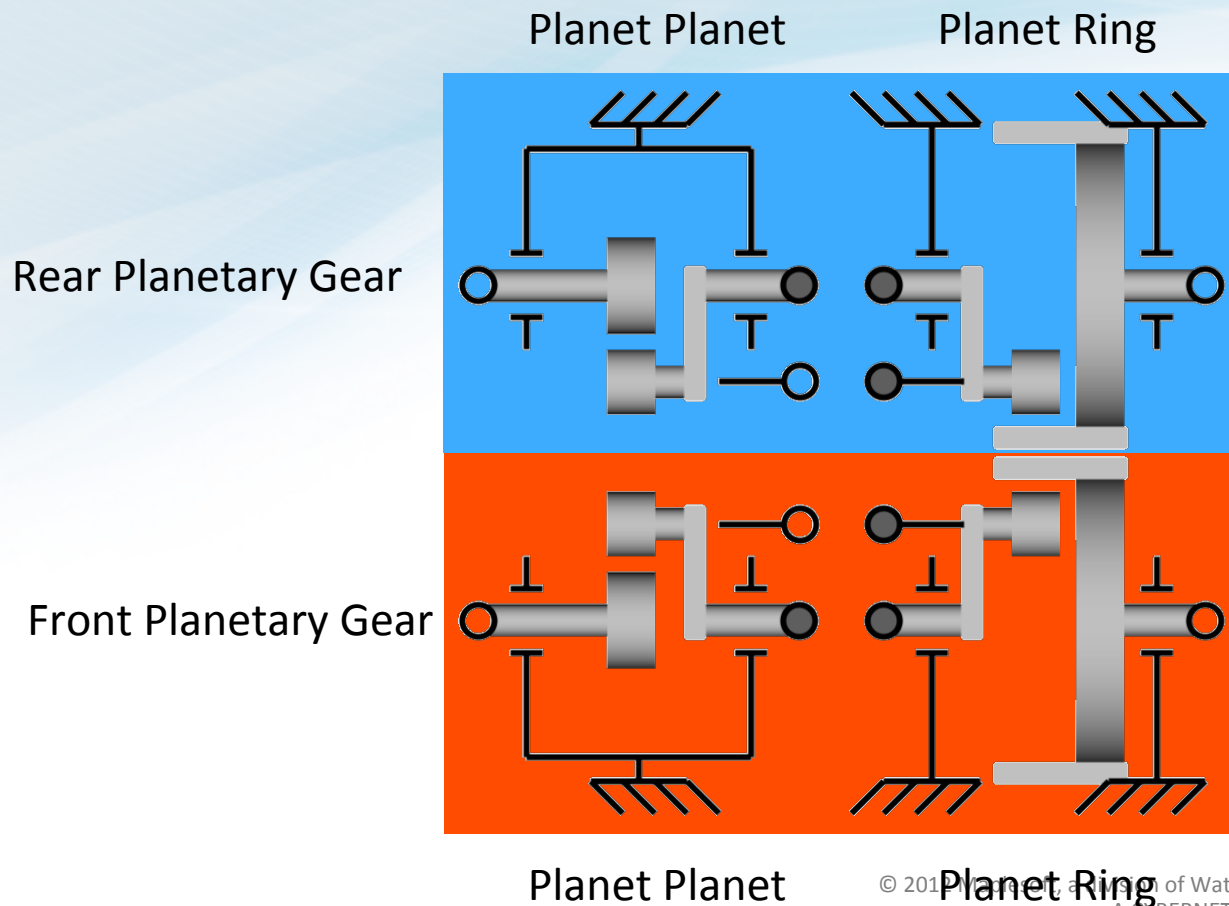
CR-CR Gear Set



Driveline Component Library

Compound Gear Sets

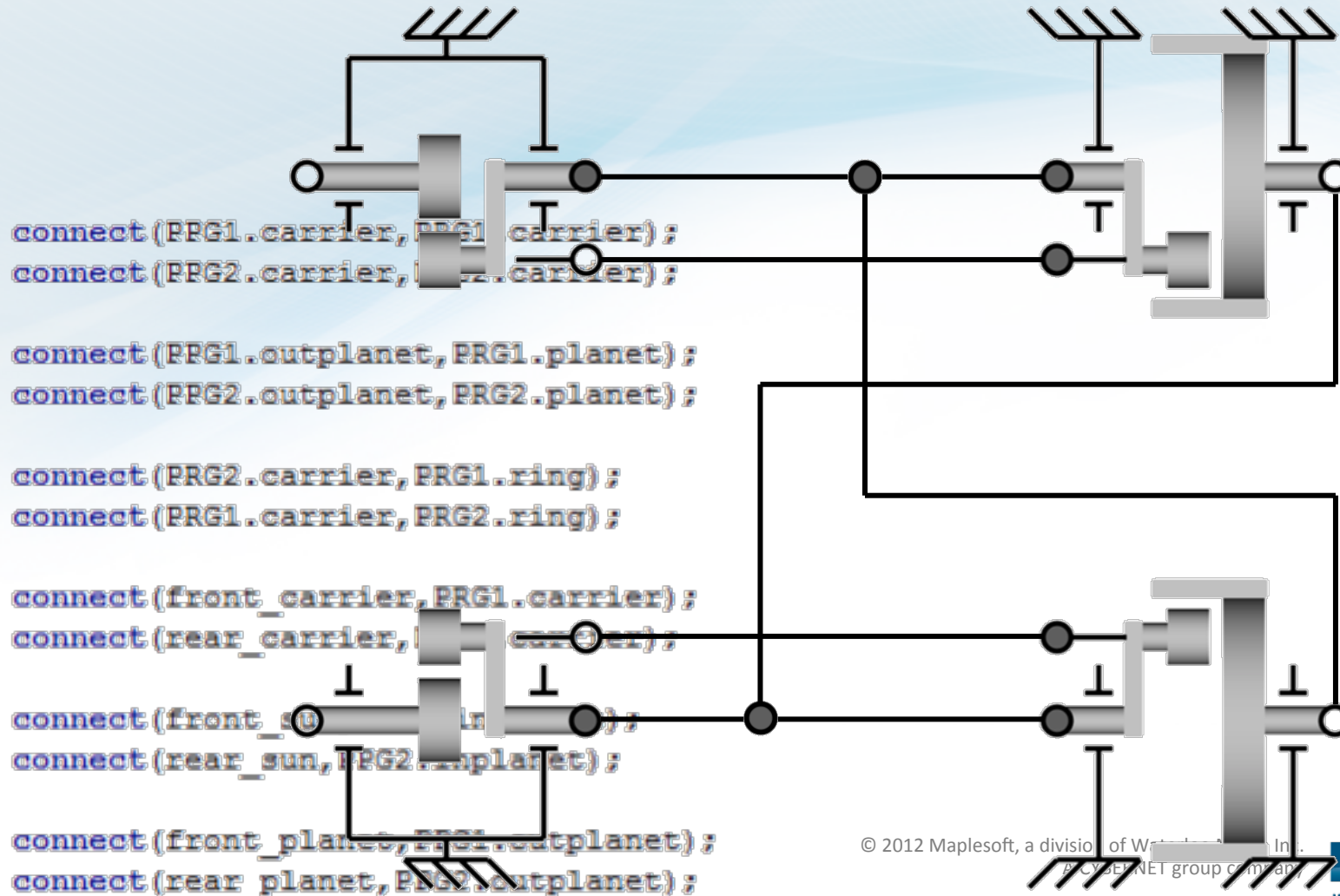
CR-CR Gear Set



Driveline Component Library

Compound Gear Sets

CR-CR Gear Set



Modeling Transmissions

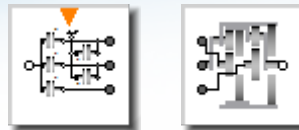
Actuation Components

Transmissions:

- Ravigneaux 4-Speed



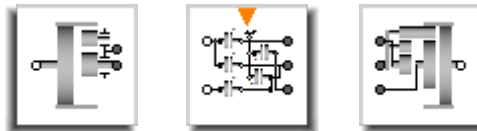
- CR-CR 4-Speed



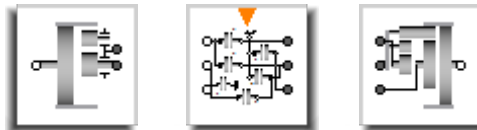
- Simpson 3-Speed



- Lepelletier 6-Speed



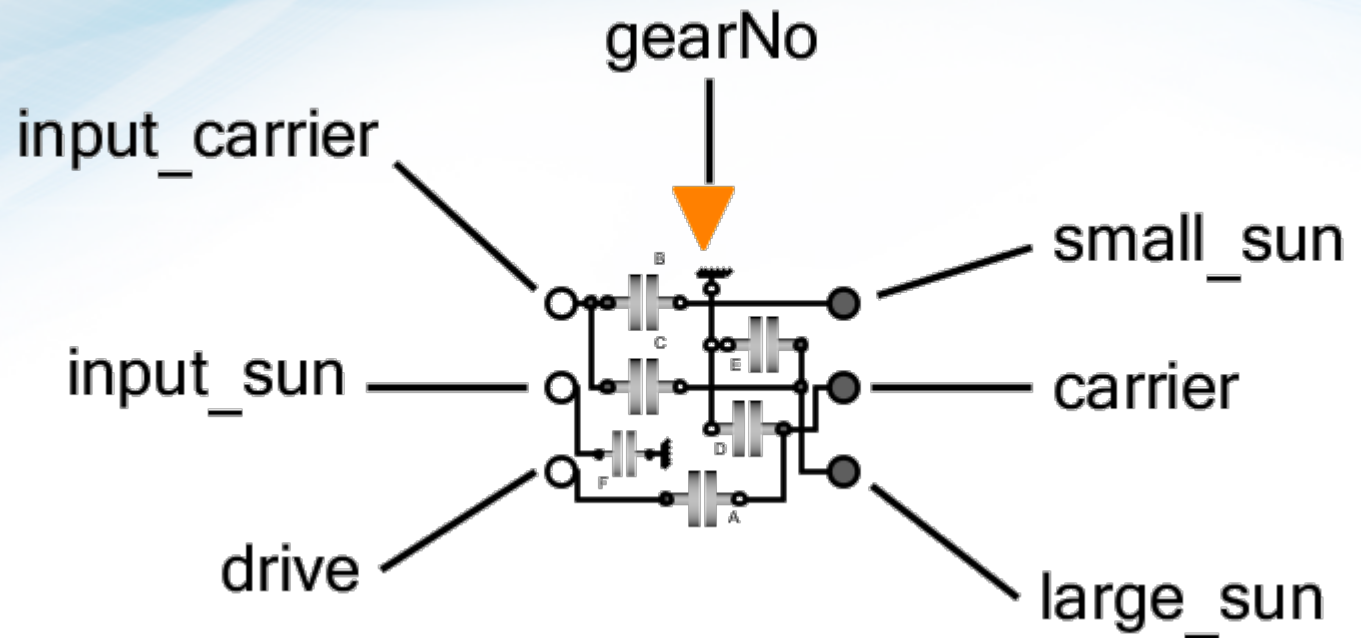
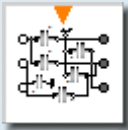
- Lepelletier 7-Speed



Modeling Transmissions

Actuation Components

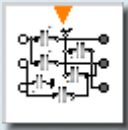
Lepelletier 7-Speed



Modeling Transmissions

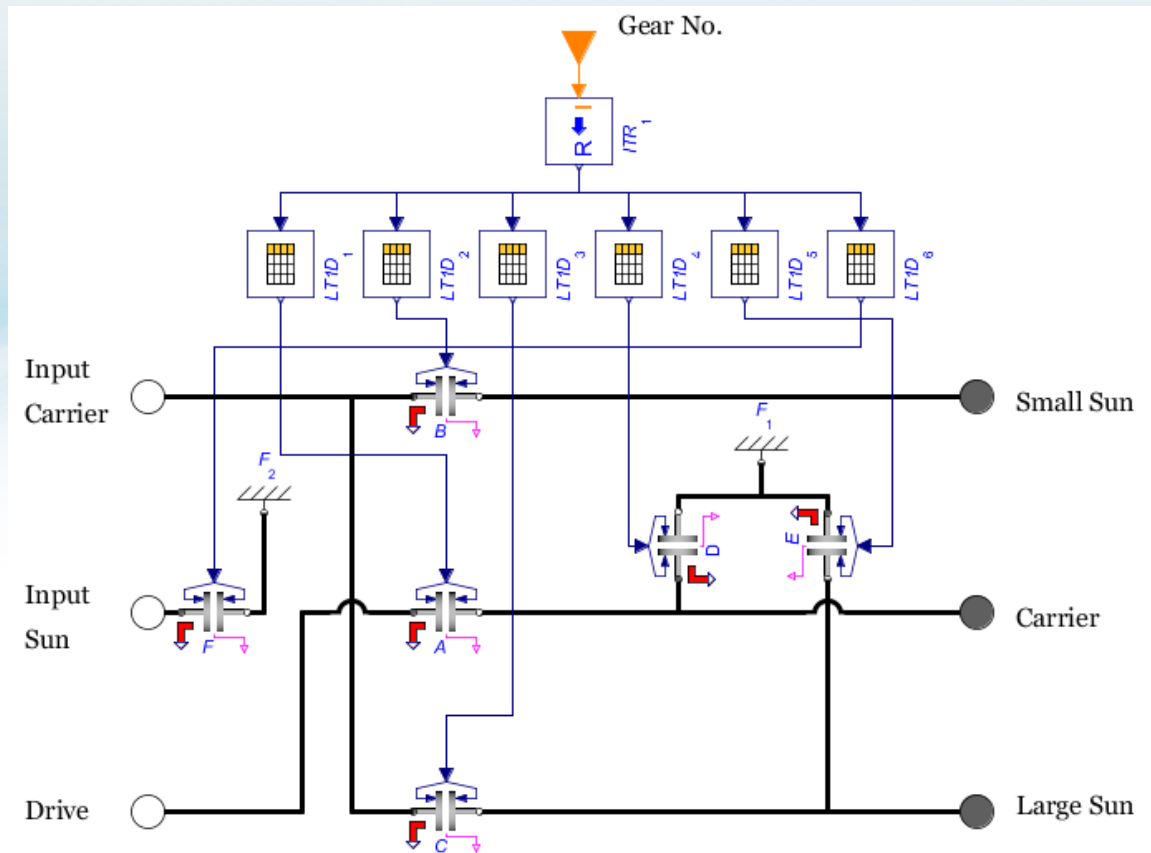
Actuation Components

Lepelletier 7-Speed



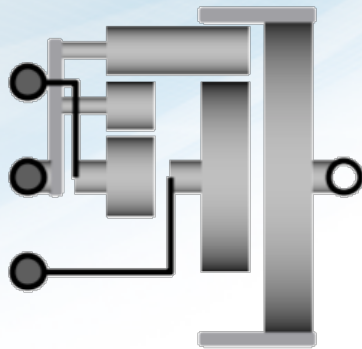
Clutch Table

Gear \ Clutch	A	B	C	D	E	F
-1	0	0	1	1	0	1
0	0	0	0	0	0	0
1	0	1	0	1	0	1
2	0	1	0	0	1	1
3	0	1	1	0	0	1
4	1	1	0	0	0	1
5	1	1	1	0	0	0
6	1	0	1	0	0	1
7	1	0	0	0	1	1



Adding Losses to Gears and Gear Sets

Option: Ideal Gear



Ravigneaux Gear

Inspector Settings Plots

Name RG_1

Type Ravigneaux Gear

▼ Parameters

▼ Modeling Parameters

ideal ←

use planet port

▼ Engineering Parameters

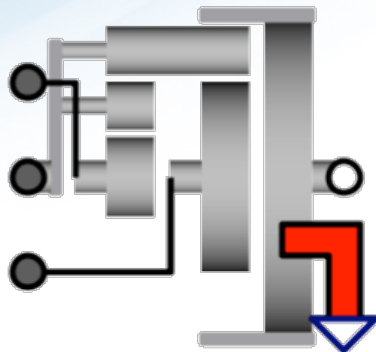
$r_{R/S}$

$r_{R/IS}$

Adding Losses to Gears and Gear Sets

Option: Lossy Gear

- Adding Meshing Friction
- Loss data is entered via:
 - GUI
 - Data File
 - External Input
- Adding Bearing Damping



Ravigneaux Gear

Inspector Settings Plots

Name

Type Ravigneaux Gear

▼ Parameters

▼ Modeling Parameters

ideal

data source

same loss data

n_{pl}

smoothness

use planet port

▼ Engineering Parameters

r_{res}

r_{ris}

$\eta_{iPIS}(\omega_{iSC})$ ←

$\eta_{oPIP}(\omega_{IPC})$ ←

$\eta_{R,oP}(\omega_{RC})$ ←

$\eta_{oPIS}(\omega_{ISC})$ ←

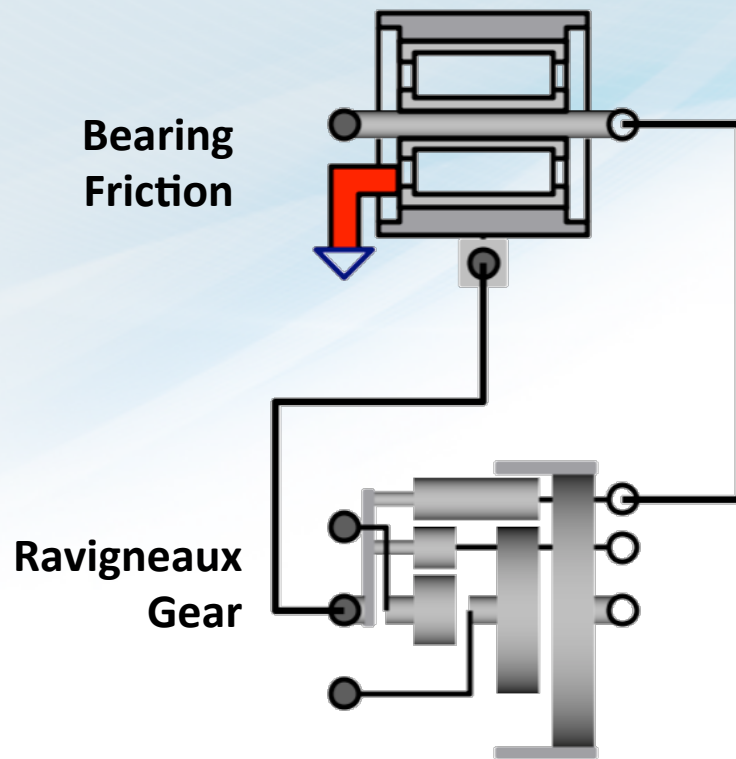
d_{IPC}

d_{oPC}

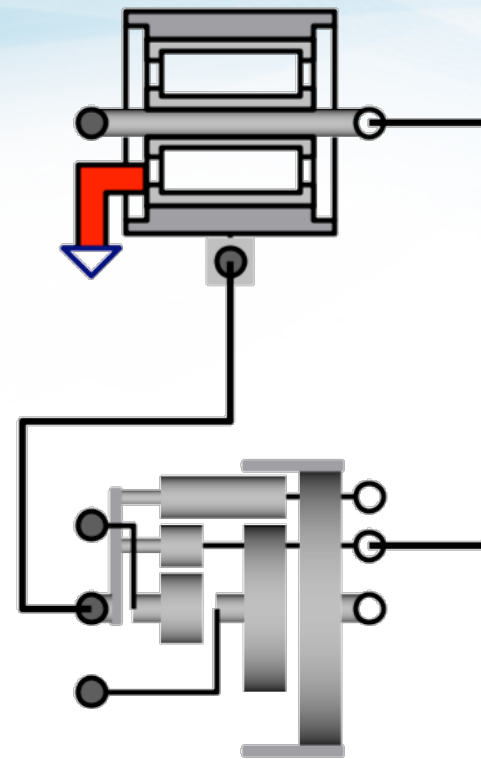
Adding Losses to Gears and Gear Sets

More Options for Modeling Losses Gears

- Adding “friction” to internal bearings

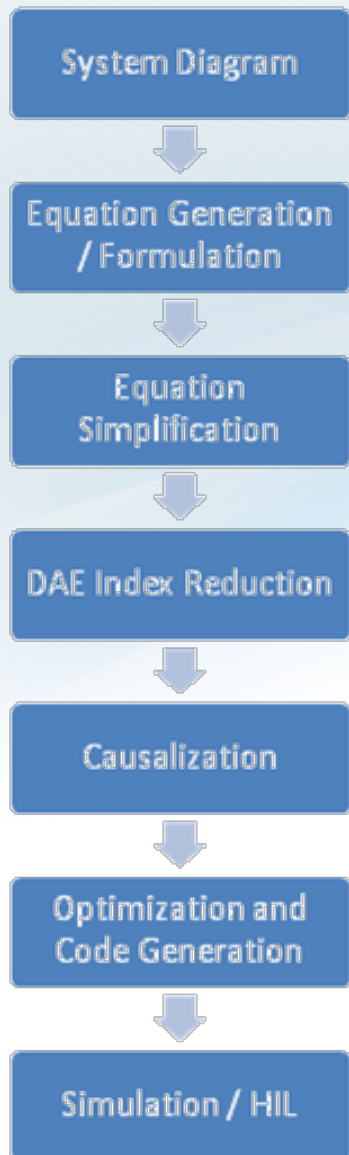


Outer Planet/Carrier
Bearing friction



Inner Planet/Carrier
Bearing friction

Advantage of the Symbolic Technology



Generation of the complete set of equations in symbolic parametric form

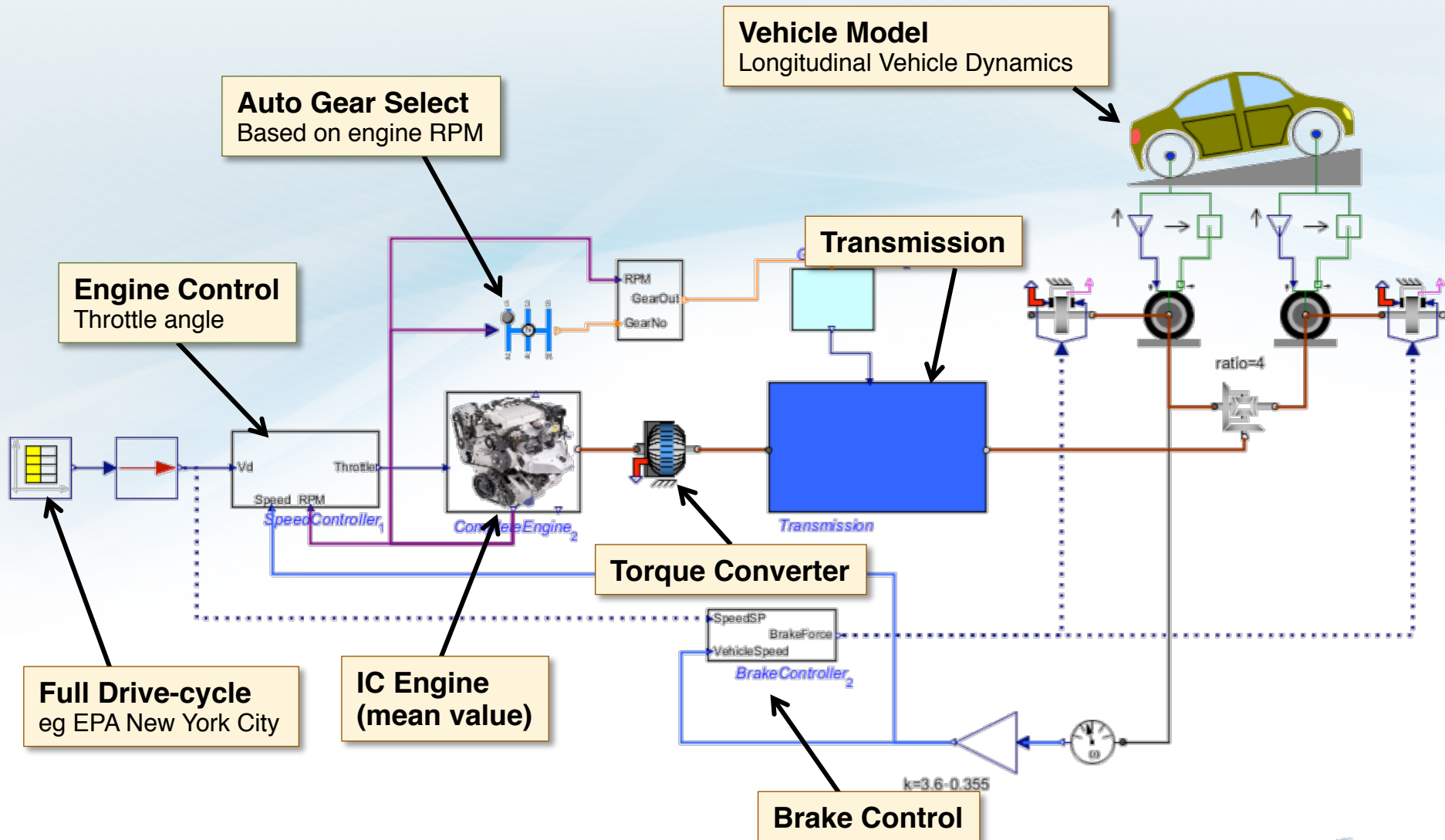
Symbolic techniques are used to simplify this set of equations as much as possible

Symbolic techniques are essential in allowing the differentiation of equations and efficient index reduction

Performed efficiently using symbolic computing based on tools from graph theory

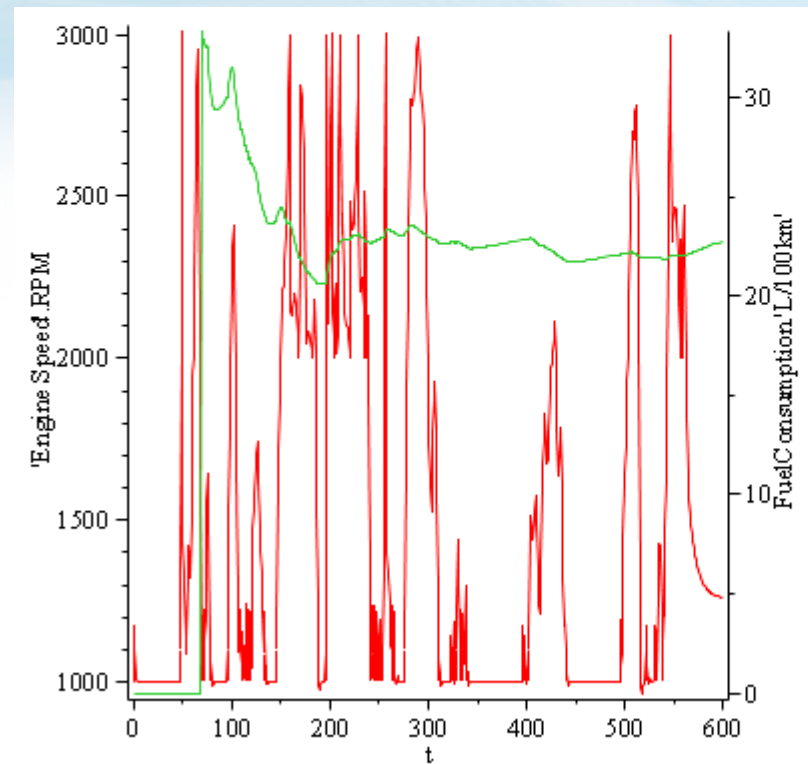
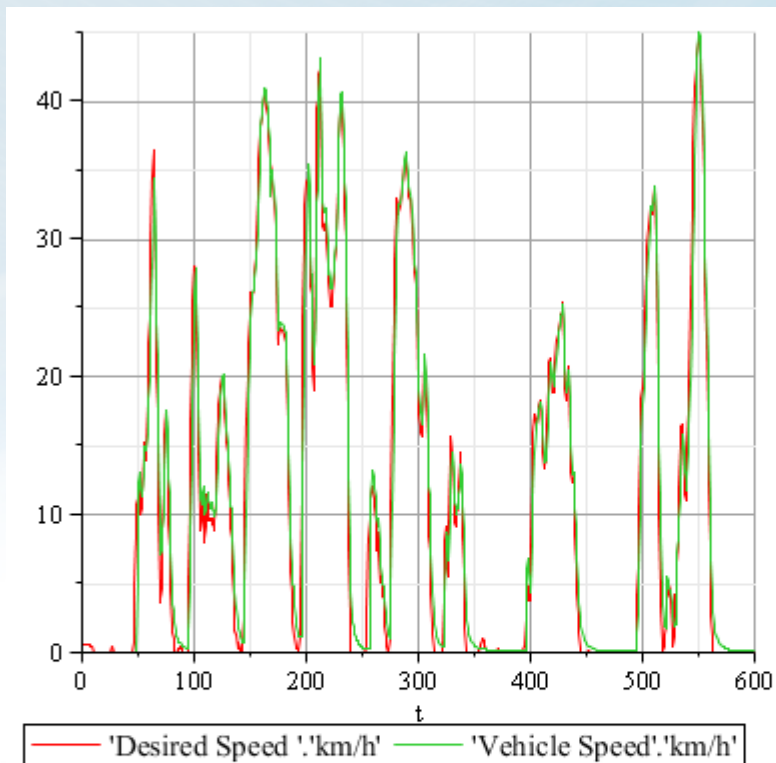
These optimizations involve detecting common computation sequences that can be factored out...

Full Powertrain Model



Full Powertrain Model

Sample simulation results



Real-time Performance

MapleSim's API

CA:\Users\ovahid\AppData\Local\Temp\Worksheet15361253931276470243.mw* - [Server 3] - Maple 15

File Edit View Insert Format Table Drawing Plot Spreadsheet Tools Window Help

Text Math Drawing Plot Animation

C 2D Input Times New Roman 12 B I U

Main ▶

```

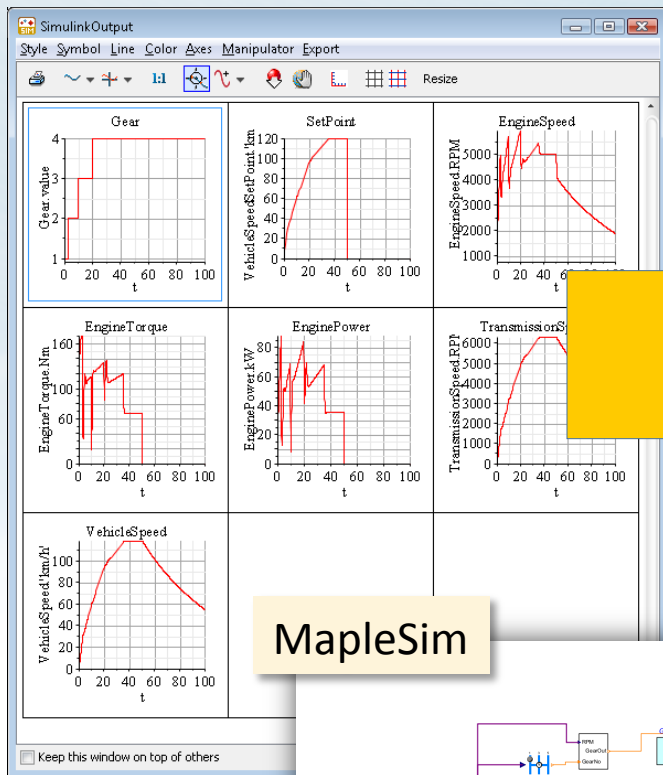
> A := MapleSim:-LinkModel( ) :
> cProc := A:-GetCompiledProc( ) :
> st := time( ) :
  results := cProc(duration = 600, dt = 0.001) :
  time( ) - st
  
```

51.527

Ready

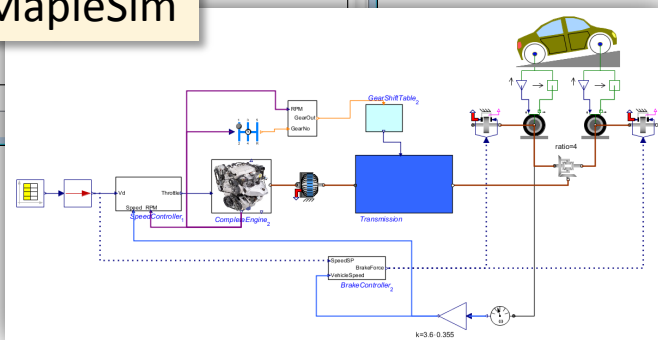
Code Generation and Export

Code Generation – Real-time Applications

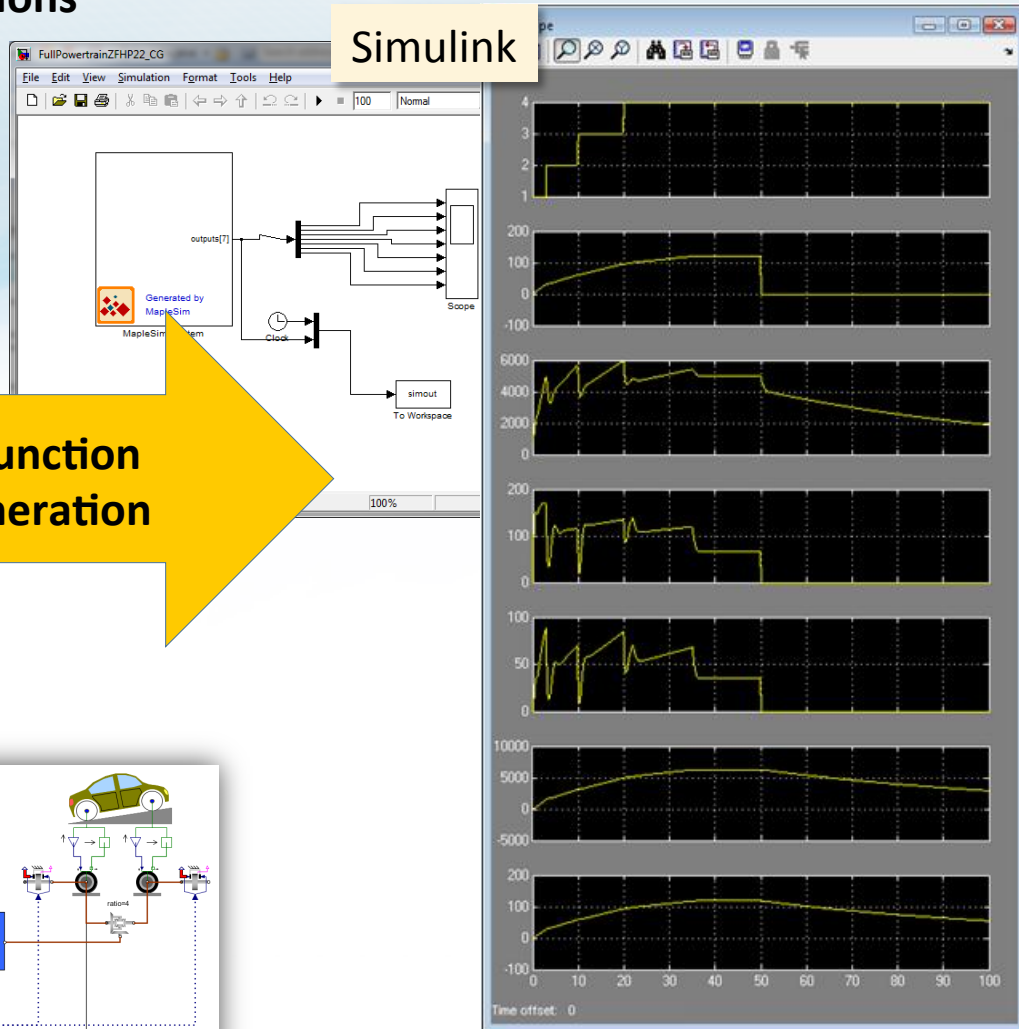


**S-function
Generation**

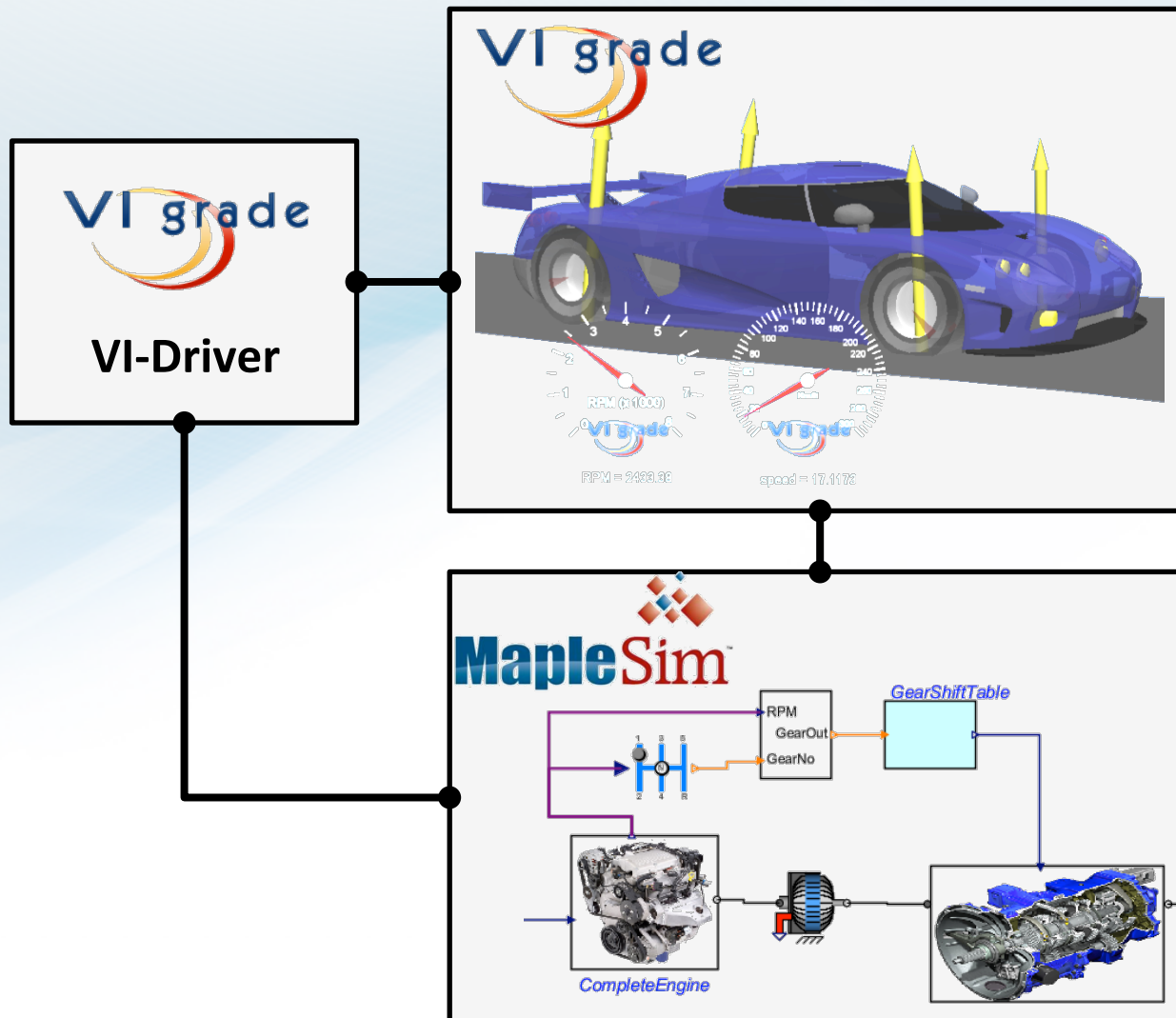
MapleSim



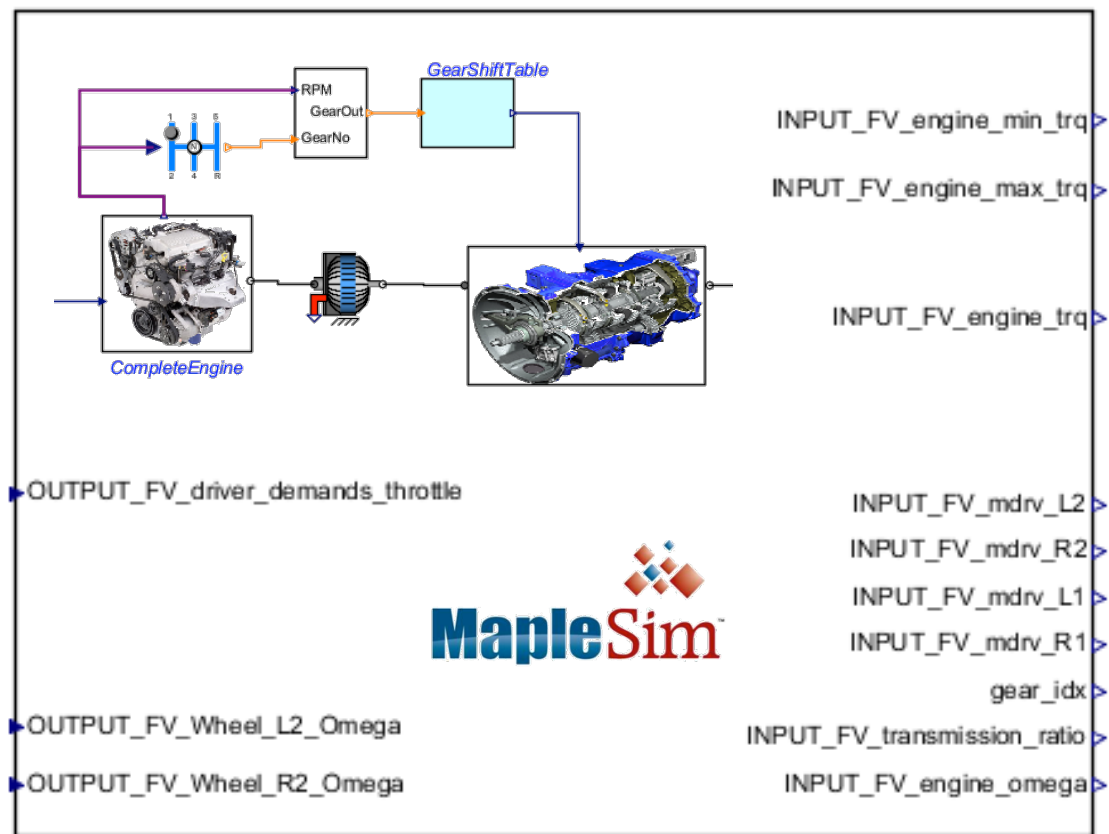
Simulink



MapleSim and VI-CarRealTime

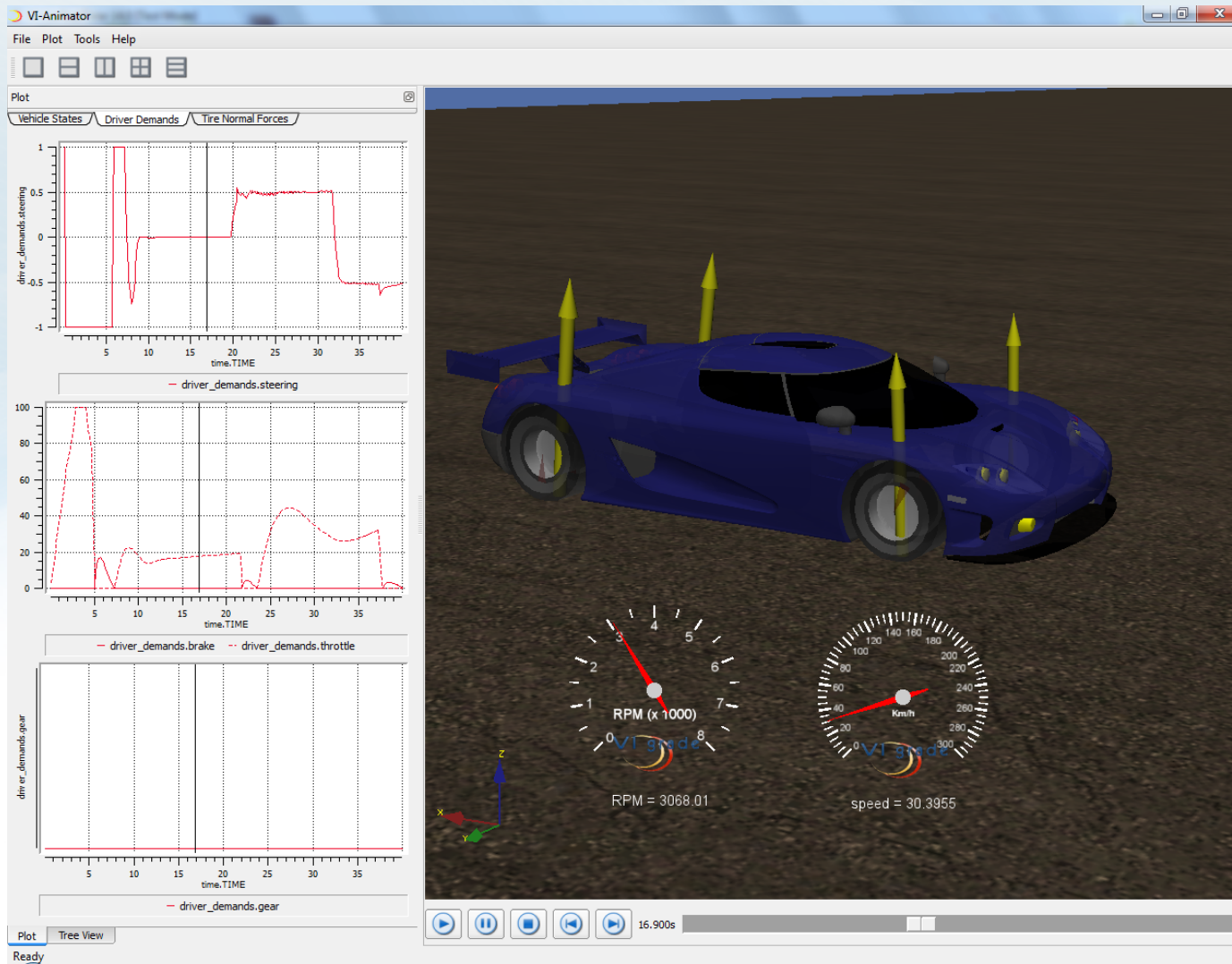


MapleSim and VI-CarRealTime



MapleSim and VI-CarRealTime

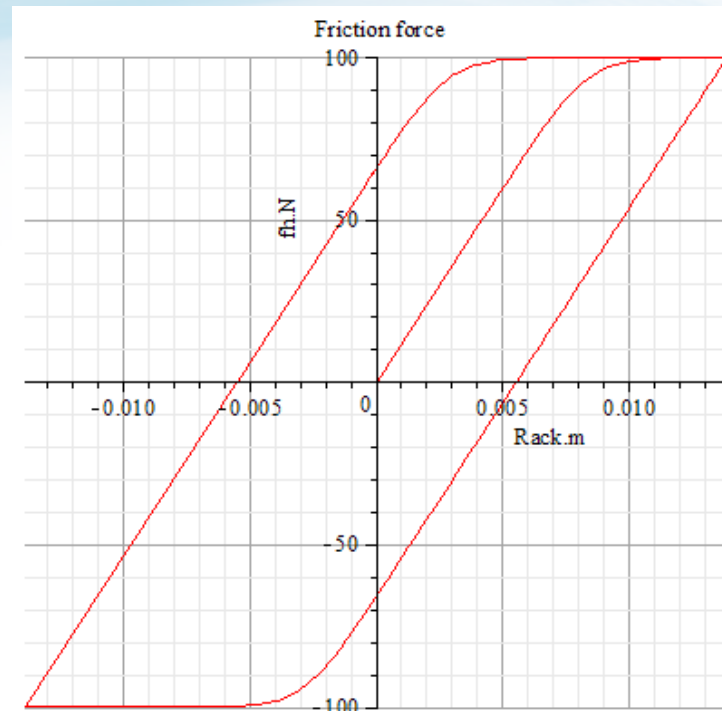
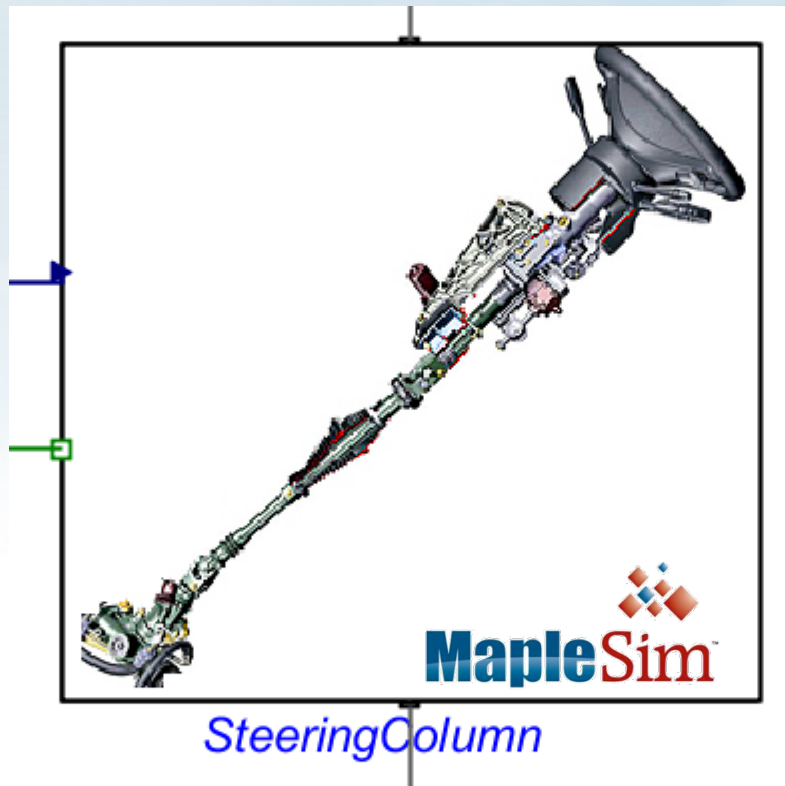
Sample Simulation Results in VI-Animator



MapleSim and VI-CarRealTime

Examples of other subsystems that can be integrated

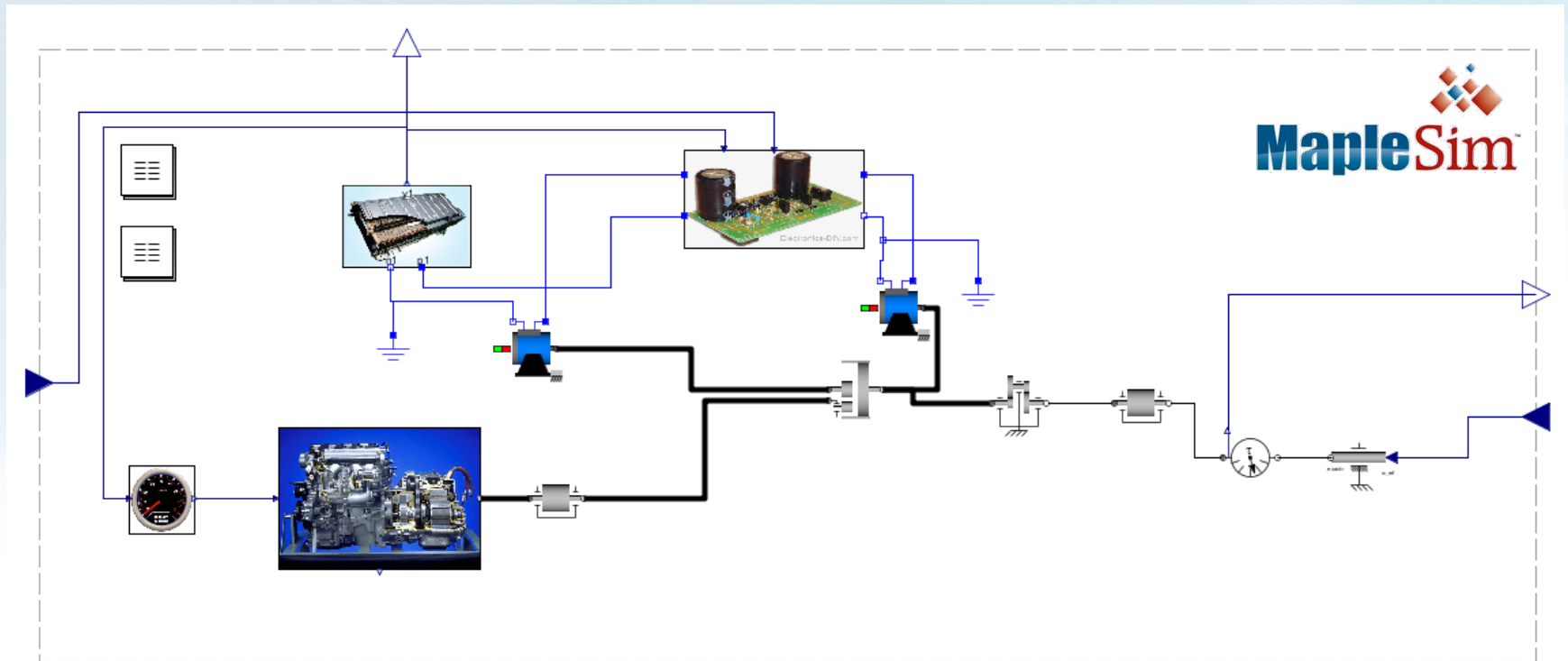
Detailed Powered Steering Subsystem



MapleSim and VI-CarRealTime

Examples of other subsystems that can be integrated

Hybrid Electric Powertrain



Summary

- **Physical modeling:** increasingly important – and increasingly complex – in automotive systems design, testing and integration.
- **Driveline Component Library:** a collection of components for modeling all stages in powertrain system – from the engine and transmission through to the differential, wheels and vehicle dynamics.
- **The Symbolic technology:** proven engineering technology that significantly improves model fidelity without sacrificing real-time performance.
- **VI-Grade** and **Maplesoft** established a partnership to make real-time modeling applications more cost and time-effective.

Thank You!

Questions?